Application of Bimodal Histogram Method to Oil Spill Detection from a Satellite Synthetic Aperture Radar Image

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Abstract: As one of segmentation techniques for Synthetic Aperture Radar (SAR) image with oil spill, we applied a bimodal histogram method to discriminate oil pixels from non-oil pixels. The threshold of each moving window was objectively determined using the two peaks in the histogram distribution of backscattering coefficients from ENVISAT ASAR image. To reduce the effect of wind speed on oil spill detection, we selected ASAR image which satisfied a limit of wind speeds for successful detection. Overall, a commonly used adaptive threshold method has been applied with a subjectively-determined single threshold. In contrast, the bimodal histogram method utilized herein produces a variety of thresholds objectively for each moving window by considering the characteristics of statistical distribution of backscattering coefficients. Comparison between the two methods revealed that the bimodal histogram method exhibited no significant difference in terms of performance when compared to the adaptive threshold method, except for around the edges of dark oil spots. Thus, we anticipate that the objective method based on the bimodality of oil slicks may also be applicable to the detection of oil spills from other SAR imagery.

Key Words: Oil Spill, SAR, Adaptive Threshold, Bimodal Histogram

1. Introduction

Synthetic Aperture Radar (SAR) sensor is one of the most important active sensors, capable of visualizing the surface of the earth. It sends a chirp pulse of microwaves at C-, K-, or L-bands to the sea surface and receives a backscattering cross section transmitted back to the sensor in space. The backscattering coefficient, or sigma naught, can be used to retrieve a variety of oceanic variables. Overall, these SAR sensor satellite systems can measure 50-500 km² regions with spatial resolutions of about 10-100 m, and are frequently...
utilized to monitor oceanic phenomena.

Ever since the primitive SAR system of Seasat launched in 1979, SAR sensors have long been used to observe the earth accurately and precisely through multi-polarization, multi-wave length, and multi-mode observations. SAR satellite data has been utilized for a wide range of marine meteorological fields, such as monitoring of ocean waves (Alpers et al., 1981; Kasischke et al., 1988; Hasselmann and Haselmann, 1991; Engen and Johnsen, 1995; Collard et al., 2005), ocean currents (Shemer et al., 1993; Graber et al., 1996; Kang and Lee, 2007), sea surface winds (Gerling, 1986; Monaldo et al., 2001; Xu et al., 2010; Kim and Park, 2011; Kim et al., 2012), and internal waves (Rodenas and Garello, 1997; Liu and Hsu, 2004), and ship detection (Ouchi et al., 2004; Liao et al., 2008), submarine detection (Liu et al., 1996), intertidal zone changes (Mason et al., 1995; Van der Wal et al., 2005), and coastal soil information (Bell et al., 2001). One other application is oil spill detection with devastating hazards along coastal regions.

One of the important preconditions for oil spill detection is an appropriate wind speed at the time, which is sufficient to generate Bragg waves. SARs measure the backscattered radar power interacted with Bragg waves in centimeter-long wavelengths at a moderate incidence angle between 20 and 70 degrees (Valenzuela, 1978). The existence of surface films significantly dampens short gravity-capillary waves (Lucassen, 1982; Huehnerfuss et al., 1983; Huehnerfuss et al., 1987; Alpers and Huehnerfuss, 1989), hence the regions covered with oil can be detected by analyzing their backscattering contrast. At low wind speeds of less than 2-3 m/s, backscattering from the sea surface as a whole tends to be very weak, so that no significant signature of oil slicks appears (Bern et al., 1992; Perez-Marrodan, 1998). Likewise, at high wind speeds of over 10-14 m/s, the damping effect disappears in the background noise of wind-generated waves (Demin et al., 1985; Bern et al., 1992; Litovchenko et al., 1999). Therefore, oil spill detection using SAR data is only applicable in a wind range of 2-14 m/s. Thus, we only utilized SAR imagery which satisfies this condition.

A variety of research for oil spill detection using SAR images has been attempted, which is important for coastal monitoring and understanding of physical oceanographic process. In most of cases, oil spills have been studied using single polarization, such as HH or VV, from European Remote Sensing 1/2 (ERS-1/2), and Environmental Satellite (ENVISAT), RADARSAT-1. Very recently, a new method has also been developed to utilize multi-polarization (HH/HV/VH/VV) SAR images in the detection of oil spills at the sea surface (Zhang et al., 2011; Migliaccio et al., 2011). However, the full polarization observation of SAR has been difficult to readily obtain due to its infrequent measurement schedule and its limitations in regards to diverse applications.

In the seas around Korea, there have been only a few studies to detect oil spills from SAR images. In addition, a relatively simple method, adaptive threshold method, has been utilized (Yang et al., 2009; Park et al., 2010; Kim et al., 2010). The adaptive threshold method has the advantage of being able to reduce computation time, but it also has a disadvantage in terms of the difficulty of setting the threshold objectively. Thus, a more robust method capable of determining the threshold objectively and automatically for operational purposes is necessary. Therefore, in this study, we introduce the bimodal histogram method for oil spill detection from SAR images with a single polarization, and then compare this method with the adaptive threshold method.

The objectives of this study are (1) to apply the adaptive threshold method algorithm to detect oil spills from an ENVISAT SAR image, (2) to develop the bimodal histogram method based on the Gaussian fitting method, and (3) to compare the two methods and present some differences.
2. Data

Since most SARs observe the sea surface with an insufficient temporal resolution, it is hard to obtain SAR imagery which includes the significant features of oil spills at the seas around Korea. Therefore, we searched European Space Agency’s (ESA) quick-look images of the world’s oceans and seas and collected SAR images which contained oil-covered areas. Among them, we selected the SAR image from ENVISAT Advanced Synthetic Aperture Radar (ASAR) off the coast of Libya in the Mediterranean Sea which showed obvious dark patches originated from natural oil seeps (Fig. 1). The SAR data was utilized to apply the oil spill detection methods and investigate the characteristics of each detection method. Details of the ENVISAT ASAR image used in this study were summarized in Table 1.

The ENVISAT ASAR image was taken at 9h 7m (UTC) on 17 September, 2006. The center of the study area is located at 14.66°E, 32.82°N. The ASAR data was obtained at C-band (5.331 GHz) with HH-polarization. The coverage of the ASAR image covers approximately 82 km in the range direction and 46 km in the azimuthal direction. The looking angle of the ASAR image ranges from 25.7° to 31.2° from nadir and the spatial resolution is 12.5 m.

In order to investigate whether or not the SAR image can be used for the detection of oil spills at the local region, we used wind speed measurements from Quick Scatterometer (QuikSCAT) at similar time to the observation time of SAR. The wind speed was 7.2 m/s for the study area in Fig. 1b, which satisfies the range limit for oil spill detection using SAR data. Overall, the thresholds of wind speed for detection were from 2-3 to 10-14 m/s (Demin et al., 1985; Bern et al., 1992; Perez-Marrodon, 1998; Litovchenko et al., 1999).

3. Method

1) Estimation of backscattering coefficient

Prior to applying oil spill detection algorithms, ENVISAT ASAR data was processed to extract the backscattering coefficients (σ₀). For ENVISAT ASAR data, an intensity of detected radar brightness was retrieved after elevation antenna patterns and range-spreading loss corrections without any incidence angle correction. Thus, the Normalized Radar Cross Section (NRCS) can be derived from detected pixel values by correcting the effect of the incidence angle. The relationship between the value of power at an image pixel, I, and NRCS is as follows:

\[ \sigma_0 = \frac{<I>}{K} \sin(\alpha) \]  

where \( < > \) indicates the spatial average of the pixel values around the target, \( \alpha \) is the incidence angle, and \( K \) is an absolute calibration constant. The derived NRCS values were converted to units of dB.

Fig. 1b shows the distribution of the derived NRCS

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ENVISAT SAR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency (GHz)</td>
<td>5.331 (C-band)</td>
</tr>
<tr>
<td>Polarization state</td>
<td>Single-polarization (HH)</td>
</tr>
<tr>
<td>Swath width (km)</td>
<td>82.83</td>
</tr>
<tr>
<td>Azimuthal range (km)</td>
<td>46.07</td>
</tr>
<tr>
<td>Resolution (m)</td>
<td>12.5×12.5</td>
</tr>
<tr>
<td>Look angle (deg)</td>
<td>25.7°–31.2°</td>
</tr>
<tr>
<td>Acquired time</td>
<td>09h 07m 18s (UTC) on 17</td>
</tr>
<tr>
<td>Central location</td>
<td>14.66°E, 32.82°N</td>
</tr>
</tbody>
</table>
values in the study area, where the bright pixels (> -16 dB) are of larger values than dark pixels (< -20 dB). The values of $\sigma_0$ ranged from -25.2 dB to -10.7 dB and the mean of the values for the entire area amounted to -15.7 dB. The dark patches on the upper middle part of the image have much lower values (dark) than those of the background data (bright). These features were assumed to be associated with the damping of Bragg resonant waves due to the presence of oil slicks.

2) Adaptive threshold method

In general, pixels which demonstrate no significant difference in terms of some environmental condition (e.g., wind speed, sea surface temperature) tend to show similar NRCS values, whereas pixels in regions covered with oil tend to contain much lower NRCS

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**Fig. 1.** (a) Location of study area (marked in a small box) and (b) distribution of backscattering cross section from ENVI SAT ASAR in the ocean near Libya on 17 September 2006.

**Fig. 2.** Flow chart of adaptive threshold method for oil spill detection, clustering the detected oil pixels, and the calculation of areas filled with oil.
values than those of the surrounding background due to the damping effect. This suggests that oil slicks are characterized by low backscattering under a certain NRCS level. If we give a proper threshold, the dark spots can be separated from the surrounding non-oil pixels at the sea surface.

The adaptive threshold method is one of the most widely used methods for oil spill detection from SAR images among those techniques which employ a threshold. Such techniques determine a threshold within each window of size $N \times N$ with a mean and standard deviation from each moving window (Vachon et al., 1998; Solberg et al., 1999). Based on these simple thresholds, pixels in a window whose NRCS values are lower than the thresholds are detected as oil spills.

Fig. 2 shows the schematic flow chart of oil spill detection for SAR data by the adaptive threshold method. Before applying the method, the input parameters including the window size, minimum cluster size in extent (km$^2$), and threshold $k$ (dB) were given. To reduce speckle noises, NRCSs were averaged in $5 \times 5$ window after land masking procedure. Using the NRCS, the adaptive threshold in a moving window was estimated and then low backscattering pixels regarded as dark spots were separated according to the threshold. To better separate the spill from its surroundings and estimate the extent of the oil-covered area, the detected dark spots were clustered using connectivity in eight neighbourhood directions. Based on the estimated extents, clusters of dark spots which were smaller than the minimum cluster size were assumed to be look-alikes and discriminated.

3) Bimodal histogram method

The bimodal histogram method separates oil spills from the sea surface based on the distribution of NRCS in a window (Skøelv and Wahl, 1993). As shown on Figs. 3a and 3b, generally a sea surface without oil has a form of histogram with unimodal distribution. On the

Fig. 3. (a) Spatial distribution of backscattering coefficient at an area without any oil spill and (b) its histogram, (c) backscattering coefficient within a window for oil spill detection based on the bimodal histogram method and (d) its histogram.
contrary, a sea surface with oil slicks shows a bimodal distribution which has two distinct peaks, since oil slicks typically have much lower NRCS values than the surrounding background (Figs. 3c and 3d). Thus, oil spills in SAR images can be identified by analyzing the form of histogram produced.

Fig. 4 shows the schematic flow chart of oil spill detection for SAR data using the bimodal histogram method. In general much of the procedure is similar to that of the adaptive threshold method, with the exception of histogram analysis and threshold determination. While the threshold of the former method was simply given based on the mean and standard deviation, that of the latter method was deduced from the characteristics of statistical distribution.

Before analyzing a form of distribution and calculating a threshold, a histogram in a moving window is fitted to multimodal Gaussian distribution functions as follows;

\[ f_\text{b}(x) = \sum_{n=1}^{N} a_n e^{-\frac{(x-b_n)^2}{c_n^2}} \]  

where \(N\) is the total number of modes, which indicates unimodal (1-peak) and bimodal (2-peak) Gaussian distributions when \(N = 1\) and \(N = 2\), respectively, and \(a_n, b_n,\) and \(c_n\) are coefficients for \(n\)th mode Gaussian fitted functions. By comparing calculated \(f_{1:3}\) and its coefficient of determination \(R^2\), it was determined which mode is the best fit to a form of histogram in a moving window.
4. Results

1) Adaptive threshold method

Fig. 5 presented the distribution of NRCS at the study area and the derived results of oil spill detection based on the adaptive threshold method. Oil slicks with rounded shapes appeared around the upper middle part of the image (enlarged images on Figs. 7a and 7b). In addition, linear or dotted dark spots assumed to be artificial structures or noises (look-alikes) were also detected to some extent. These small dark spots can be discriminated by setting minimum cluster size. In this study, we set the minimum cluster size to a value of 0.1 km$^2$ in order to remove these look-alikes. After clustering and discrimination, the extent of the dark spots was calculated. The extent of the dark spots detected by the adaptive threshold method was estimated to be 1.87 km$^2$.

2) Bimodal histogram method

To detect oil spills the bimodal histogram method was also applied. Fig. 6 demonstrates an example of a threshold determined using the bimodal threshold method. A histogram of a window shows a typical form of bimodal distribution. The values of for Gaussian fitted functions were 0.01 ($f_1$), 0.51 ($f_2$), and 0.87 ($f_3$), respectively. We fitted the histogram to the Gaussian function and found peaks of bimodal distribution. A threshold in each window was set to the middle point of two peaks. While thresholds determined by the adaptive threshold method vary with a moving window (i.e., a value of threshold decreases as more pixels of oil are included in a window, and vice versa), locations of the peaks in a bimodal histogram are rarely affected by the size of the window. This method is not a subjective method, but rather an objective method that does not require any a prior knowledge of backscattering coefficients as a threshold. It can be automatically determined in a series of algorithms. Thus, the bimodal histogram method is seems to yield a more consistent result. It is known as an elaborate and efficient method for detecting oil spills which are not too thin (Brekke and Solberg, 2005).

For the ENVISAT ASAR image in Fig. 7a, we applied the bimodal histogram method described herein and obtained the analysis result of oil spill pixels in Fig. 7c. Number 1 corresponds to oil pixels. The two dark spots seem to be relatively well detected in comparison...
to the original backscattering coefficients (Fig. 7a). The result is similar to that obtained with the adaptive threshold method.

3) Comparison of detection methods

In order to illustrate the differences between the two detection methods, we compared the analysis results of the bimodal histogram method with those of the adaptive threshold method. First of all, we subtracted the flag numbers of Fig. 7c from those of Fig. 7b. Differences ranged from -1 to 1 as shown in Fig. 7d. Dominant differences appeared at the boundaries of the detected dark spots.

The circular pattern in Fig. 7d exhibited both positive and negative values for both small and large oil spots. Detailed examination of the oil flags showed that pixels with a difference of 1 were a little larger than those of -1. The total area of dark spots detected by the bimodal histogram method was estimated to be 1.74 km$^2$, which were slightly smaller and more rounded than those detected by the adaptive threshold method.

The distribution of differences between the two methods indicated that the bimodal histogram method has a tendency to somewhat underestimate the extent of oil spills. However, those differences were fairly small, amounting to less than 8% of the total extent of oil spill. Therefore, it can be inferred that there is no substantial difference between the two methods in terms of their results.

5. Summary and Conclusion

Oil spills in the ocean have had devastating effects upon the environment, particularly in terms of fisheries and biological activities. Thus, it is necessary to develop an accurate method for detecting such spills. Detection techniques for oil spills have long been in development, with most of the previous literature relying upon the adaptive threshold method, due to its simplicity in terms of calculation. However, the threshold determined with this method tends to be subjective in most of cases. Therefore, it may be somewhat less accurate and should be developed in a more objective way.

In this study, we applied the bimodal histogram method.
method to an ENVISAT ASAR image with oil spills which satisfied the limit of wind speed, and then compared the results with those from the previous method. Until now, most of oil spill detection from SAR data have depended solely upon the adaptive threshold method. Since the method is fairly subjective, this study attempts to apply a more objective threshold method based on the statistical characteristics of bimodality of histogram. When compared with the results from the adaptive threshold method, the bimodal histogram method shows no significant difference, with the exception of negligibly small errors at the boundaries of dark spots. This implies that a method utilizing an objective threshold, such as the bimodal histogram method used in this study, has an applicability for oil spill detection in other SAR imagery in other oceanic regions.

In addition to the two methods introduced here, other methods have been developed for oil detection in SAR images, such as the neural network method, decomposition analysis, or the conformity coefficient method. However, these methods need more in-situ measurements of oil and reference data, or full-polarized SAR data to yield the results. The method used in this study does not require any prior knowledge of backscattering coefficients as a threshold. In addition, it does not require any polarization, such as HH, VV, or HV. Thus, this study is expected to make a contribution to the monitoring and detection of oil spills in the ocean, in an automatic and objective manner suitable to the use of SAR images.

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