Evaluating Interval Estimates for Comparing Two Proportions with Rare Events

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Abstract

Epidemiologic studies frequently try to estimate the impact of a specific risk factor. The risk difference and the risk ratio are generally useful measurements for this purpose. When using such measurements for rare events, the standard approaches based on the normal approximation may fail, in particular when no events are observed. In this paper, we discuss and evaluate several existing methods to construct confidence intervals around risk differences and risk ratios using Monte-Carlo simulations when the disease of interest is rare. The results in this paper provide guidance how to construct interval estimates of the risk differences and the risk ratios when no events are detected.

Keywords: Bayesian probability interval, confidence interval, rare events, risk ratio, risk difference.

1. Introduction

In epidemiologic research estimates of disease frequency are the basis for the comparison of populations and the identification of disease determinants. The comparison of two frequencies can be combined into a single summary parameter that estimates the association between an exposure and the risk of developing a disease. This can be accomplished by calculating the risk difference and the risk ratio. The risk difference (RD) is defined as the difference between the risk in the exposed and non-exposed groups and provides information about the absolute effect of the exposure or the excess risk of disease in those exposed over those non-exposed. The RD describes the absolute change in risk attributable to the exposure and is useful in answering the question how much of the disease can be prevented if the exposure in question is eliminated. In epidemiology a more frequent measure of the difference between two proportions is their ratio referred to as the risk ratio, rate ratio, or relative risk, depending on the type of study. A risk ratio (RR) or relative risk is the ratio of the incidence of disease in the exposed group divided by the corresponding incidence of disease in the non-exposed group.

Both RD and RR can be used to determine the existence and the strength of an association between exposure and outcome in cohort studies but are not appropriate for the analysis of case-control
studies. Instead, the odds ratio (OR) is used in case-control studies, another measurement of the association between exposure and outcome. The OR is often referred to as approximate relative risk because the OR can be used as an estimate of RR when the incidence of disease is very low.

Suppose $x_1$ and $x_2$ are disease frequencies of two independent populations with sizes $n_1$ and $n_2$ respectively. The RD and the RR are defined by $p_1 - p_2$ and $p_1/p_2$ respectively where $p_1$ and $p_2$ are the probabilities of disease in two populations. The standard methods of constructing confidence interval (CI) of RD and RR are based on normal approximation, these are used widely in most of statistical software packages by non-statisticians. Along with the computational simplicity, the CI of RD has an apparent advantage of producing interval centered on the point estimate, thus resembling one for the mean of a continuous normal variate. In addition, the CI of RR generally has the asymptotic normality of the natural logarithm of an observed ratio.

However, when $x_1 = x_2 = 0$, we have a problem with using the interval estimates of RD and RR. The CI of RD is zero length, and the CI of RR is not defined. The situation in which no cases occur in a binomial experiment arises quite frequently when $p_1$ and $p_2$ are small. Examples are an epidemiologic study where disease of interest is a rare event and a diagnostic test in which it is common to deal with a small false negative rate (the probability of a disease individual testing negative). Newcombe (1998a, 1998b) has studied interval estimation of single proportion and the difference of two independent proportions. Newcombe (1998b) examined risk differences (RDs) in symmetry and aberrations as well as degree of coverage based on various sample parameter space points. Two types of aberrations are classified based on the location of the interval and the expected interval width as tethering and overt overshooting. Tethering occurs if either the calculated upper and lower limits coincide with the point estimate. Overt overshooting occurs if either calculated limit is outside the boundaries. These aberration problems can occur in the analysis of rare events.


All of these studies focused on improving the performances of interval estimates in studies with a small sample size. Chan (1998) proposed exact tests of equivalent and efficacy that are desirable for studies with small sample sizes. To our knowledge, our simulation experiment is the first comparative study for interval estimates of the RD and the RR with small probabilities of the disease case.

This paper discusses interval estimates, the CI of RD and RR, when there is a small probability of a disease under investigation to occur. In contrast to the $p$-value the use of the CI to interpret a result has the advantage that the CI is measured with the same scale of data while the $p$-value is a probabilistic measurement. The CI conveys information about magnitude and precision of effect. A point estimate is of limited value without some indication of its precision. This is provided by the CI (Newcombe, 1998a).

Our paper is divided in 4 sections. In the following Section 2, we describe interval estimates for RD and RR. In Section 3 examples are shown to highlight problems. Simulation results using Monte-Carlo methods are provided in Section 4. The findings are discussed at the end of the paper.
2. Various Interval Estimates

2.1. Risk difference

Newcombe (1998b) evaluated several existing methods to estimate the CI for the difference between two proportions. He concluded that the profile likelihood based method produces the best coverage probabilities, though it may be difficult to calculate for a large denominator. The Wilson score method is known to have good coverage probabilities for small and medium size data. In this subsection, we will describe four RD interval estimates (that include profile likelihood based and Wilson score method) that in most circumstances perform well. A simple asymptotic method used in most software packages (the Wilson score method, the exact method, and the Bayesian probability method) are discussed here. When the number of observations is small, the exact method has the same logic framework as the profile likelihood based method familiar to StatXact users. The exact method of StatXact is used in this paper as an alternative of profile likelihood based method. The Bayesian probability method is included because it yields the interval estimates of a proportion in a one sample problem close to the exact confidence interval when no cases are observed (Louis, 1981).

1. Normal approximation (NA)

The interval estimate of RD based on the normal approximation is given as

\[
(p_1 - p_2) \pm z_{\alpha/2} \sqrt{\frac{p_1(1-p_1)}{n_1} + \frac{p_2(1-p_2)}{n_2}},
\]

where \( p_1 = x_1/n_1 \) and \( p_2 = x_2/n_2 \). This method gives good results for large prospective studies, while these limits yield an interval of (0, 0), a tethering when \( x_1 = x_2 = 0 \).

2. Wilson score method (WS)

The 100(1 - \( \alpha \))% confidence interval (L, U) of the Wilson score method is given as

\[
L = \hat{p}_1 - \hat{p}_2 - \delta, \quad U = \hat{p}_1 - \hat{p}_2 + \epsilon
\]

where

\[
\delta = \sqrt{\left(\frac{x_1}{n_1} - l_1\right)^2 + \left(\frac{x_2}{n_2} - u_2\right)^2} = z_{\alpha/2} \sqrt{\frac{l_1(1-l_1)}{n_1} + \frac{u_2(1-u_2)}{n_2}},
\]

\[
\epsilon = \sqrt{\left(\frac{x_1}{n_1} - l_1\right)^2 + \left(\frac{x_2}{n_2} - u_2\right)^2} = z_{\alpha/2} \sqrt{\frac{l_1(1-l_1)}{n_1} + \frac{u_2(1-u_2)}{n_2}},
\]

\( l_1 \) and \( u_1 \) are the roots of \( |p_1 - x_1/n_1| = z_{\alpha/2} \sqrt{p_1(1-p_1)/n_1} \), and \( l_2 \) and \( u_2 \) are the roots of \( |p_2 - x_2/n_2| = z_{\alpha/2} \sqrt{p_2(1-p_2)/n_2} \) (Wilson, 1927). When \( x_1 = x_2 = 0 \), they are \( 0 = l_1 < u_1 < 1 \) and \( 0 = l_2 < u_2 < 1 \) and \( \delta \) and \( \epsilon \) become \( u_2 \) and \( u_1 \) respectively. Therefore, (L, U) of the Wilson score method have no aberrations.

3. Exact method (EX)

Let \( \theta = p_1 - p_2 \) and \( \psi = p_2 \). Consider a test of \( H_0(x) : p_1 - p_2 = x \) versus \( H_1 : p_1 - p_2 \neq x \). We reject \( H_0(x) \) when \( |\hat{p}_1 - \hat{p}_2 - x| \) is larger than the critical value \( C_x \). If we know the true value of \( \psi \), then the critical value \( C_x \) is calculated for a given level \( \alpha \) by

\[
Pr\{|\hat{p}_1 - \hat{p}_2 - x| > C_x|\theta = x, \psi\} = \frac{\alpha}{2}.
\]
Now, we can construct the exact $100(1 - \alpha)\%$ confidence interval $(L, U)$ by
\[
L = \inf\{x : H_0(x) \text{ is not rejected}\},
\]
and
\[
U = \sup\{x : H_0(x) \text{ is not rejected}\}.
\]
See Bickel and Doksum (1977, p.155). However, we don’t know $\psi$. One simple remedy for this problem is to eliminate nuisance parameter $\psi$ by taking supremum over its range suggested by Santner and Snell(1980). Berger and Boos(1994) suggested a modified method of searching supremum and eliminating in a restricted range. As a first step, an exact $100(1 - \gamma)\%$ intervals for $p_1$ and $p_2$ are computed. Denote those intervals as $A_1 = [l_1, u_1]$ and $A_2 = [l_2, u_2]$ respectively. Assume that the event $\varepsilon : (p_1, p_2) \in A_1 \times A_2$ is true. Then $100(1 - \alpha)\%$ exact confidence interval $(L, U)$ in restricted range $(l_2 - u_1, u_2 - l_1)$ is given that satisfies the conditions
\[
\sup_{\psi \in \varepsilon^*} \Pr (\hat{p}_1 - \hat{p}_2 \leq x | L = x, \psi) = \frac{\alpha}{2} - \gamma,
\]
\[
\sup_{\psi \in \varepsilon^*} \Pr (\hat{p}_1 - \hat{p}_2 \geq x | U = x, \psi) = \frac{\alpha}{2} - \gamma,
\]
where $\varepsilon^* = \{p_2 : \max(l_2, l_1 - x) \leq p_2 \leq \min(u_2, u_1 - x)\}$.

The intervals $(l_i, u_i)$, $(i = 1, 2)$ are calculated within $(0, 1)$ from the two independent binomial distributions and the interval $(L, U)$, as mentioned, is always in restricted range $(l_2 - u_1, u_2 - l_1)$, which is narrower than boundary $(-1, 1)$. This modified method can provide stability, narrower CI, and faster execution by cutting off regions near the extremes of the parameter space.

4. **Bayesian probability method (BP)**

The Bayesian probability interval of RD is constructed as follows. Let $\pi(p_1, p_2)$ be the prior distribution of $(p_1, p_2)$. Then the posterior distribution is given by
\[
\pi(p_1, p_2 | x_1, x_2) \propto p_1^{x_1}(1 - p_1)^{n_1 - x_1} p_2^{x_2}(1 - p_2)^{n_2 - x_2} \pi(p_1, p_2).
\]

Let $\theta = p_1 - p_2$ and $\psi = p_1 + p_2$, and let $\pi(\theta, \psi | x_1, x_2)$ be the corresponding posterior distribution of $\theta$ and $\psi$, which can be obtained by using the variable transformation technique. Now, the equal tail $100(1 - \alpha)\%$ probability interval has the form of $(L, U)$ which satisfies
\[
\int_U^1 \int_0^2 \pi(\theta, \psi | X_1, X_2) d\psi d\theta = \frac{\alpha}{2}
\]
and
\[
\int_{-1}^L \int_0^2 \pi(\theta, \psi | X_1, X_2) d\psi d\theta = \frac{\alpha}{2}.
\]
See Gelman et al. (1995). In practice, we can obtain $L$ and $U$ by using a simple Monte-Carlo method as follows. First, we generate $p_1$ and $p_2$ from their posterior distributions and calculate $\theta = p_1 - p_2$. We repeat this several times to get many $\theta$s generated from the posterior distributions. Finally, $L$ and $U$ are obtained from the histogram of $\theta$s.
2.2. Risk Ratio

Gart and Nam (1988) grouped several RR interval estimates into three categories based on their mode of derivation, which are the normal approximate methods, the Fieller-like method, and the likelihood based method. In this subsection, we briefly describe these three methods along with the Bayesian probability method.

1. Normal approximation (NA)

There are two approaches to construct the CI of RR; the delta method and the exponential transformation. The delta method is to compute the CI of RR using delta rule to derive an estimate of standard error (SE) while the exponential transformation method is to transform RR exponentially to approximate normal, then transformed end-points of the CI in the natural parameter space. Asymptotically, these two are equivalent; however, they will differ for real data.

The 100\((1 - \alpha)\)% CI by using delta method is

\[
\left( \frac{\hat{p}_1}{\hat{p}_2} \right) \left( 1 \pm z_{\alpha/2} \sqrt{\frac{1 - \hat{p}_1}{n_1\hat{p}_1} + \frac{1 - \hat{p}_2}{n_2\hat{p}_2}} \right),
\]

where \(\hat{p}_1 = x_1/n_1\) and \(\hat{p}_2 = x_2/n_2\).

In practice, the CI obtained by transforming the end-points has some intuitively desirable properties, for example, they do not produce negative RR. In general, we also expect the estimates to be more normally distributed. The 100\((1 - \alpha)\)% approximate CI of RR used in this paper is one using the exponential transformation method and is given as

\[
\exp \left[ (\log(\hat{p}_1) - \log(\hat{p}_2)) \pm z_{\alpha/2} \sqrt{\frac{1 - \hat{p}_1}{n_1\hat{p}_1} + \frac{1 - \hat{p}_2}{n_2\hat{p}_2}} \right],
\]

where \(\hat{p}_1 = x_1/n_1\) and \(\hat{p}_2 = x_2/n_2\). The limits are not defined when either or both of \(x_1\) and \(x_2\) are zero.

2. Fieller-like method (FL)

Denote \(\phi = p_1/p_2\). The Fieller-like interval uses the statistic \(T = \hat{\phi} - \phi\) where \(\hat{\phi} = \hat{p}_1/\hat{p}_2\). It can be shown that \(T\) is asymptotically normal with variance

\[
\text{var}(T) = \frac{\phi^2 q_2}{n_2 p_2} + \frac{\phi^2 q_1}{n_1 p_1}.
\]

\(p_1\) in this variance formula is substituted by \(\phi p_2\) and \(p_2\) is estimated by \(\hat{p}_2\). Finally, the 100\((1 - \alpha)\)% confidence interval using this estimated variance \(V(T)\) is given as the solution of following quadratic equation;

\[
\left( \hat{\phi} - \phi \right)^2 = z_{\alpha/2}^2 V(T).
\]

This Fieller-like interval estimate is proposed by Noether (1957). A different type of Fieller-like interval estimates for RR based on the statistic \(T' = \hat{p}_1 - \phi \hat{p}_2\) has been proposed by Katz et al. (1978). If both \(x_1\) and \(x_2\) are greater than zero, the equation always yields real roots. However, when \(x_2 = 0\) the variance and the point estimate \(\hat{\phi}\) are not defined. When \(x_1 = 0\) and \(x_2 \neq 0\), one limit becomes zero, which is a tethering and the other limit may be less than zero. When \(\hat{p}_2\) is very
small, these roots may be complex or may be exclusive such like disjoint confident interval, that is, 
(0, a) and (b, ∞) where b > a.

3. Likelihood based method (LB)
Miettinen and Nurminen (1985) have proposed a method that uses the maximum likelihood estimator (MLE) of the nuisance parameter \( p_2 \), for a given value of \( \phi = p_1/p_2 \). Let \( \hat{p}_2 \) be the MLE of \( p_2 \) given \( \phi \) and let \( \hat{p}_1 = \phi \hat{p}_2 \). The MLE of \( p_2 \), \( \hat{p}_2 \) is the appropriate solution to the quadratic equation

\[
a \hat{p}_2^2 + b \hat{p}_2 + c = 0,
\]

where \( a = (n_1 + n_2)\phi, b = -[(x_2 + n_1)\phi + x_1 + n_2], \) and \( c = x_1 + x_2 \). They started with the statistic \( T = \hat{p}_1 - \phi \hat{p}_2 \) and estimated its variance by \( \hat{p}_1 \hat{q}_1/n_1 + \phi^2 \hat{p}_2 \hat{q}_2/n_2 \). Then, they obtained the limits of 100(1 - \( \alpha \))% confidence interval as the roots to the equation

\[
\frac{(\hat{p}_1 - \phi \hat{p}_2)^2}{(\hat{p}_1 \hat{q}_1)/n_1 + (\phi^2 \hat{p}_2 \hat{q}_2)/n_2} = \frac{z^2}{2}.
\]

(2.7)

Koopman (1984) derived the same confidence interval from different derivation. Gart and Nam (1988) showed Miettinen and Nurminen method and Koopman’s method are identical. The only difference is that Miettinen and Nurminen use a variance correction, so the resulting limits are slightly wider than those given by Koopman’s formulation. When \( x_1 \) and \( x_2 \) are zero, the variance is not defined because the MLE of the nuisance parameter \( p_2 \) becomes zero. If either \( x_1 \) or \( x_2 \) is zero, only one limit is found because the left term of (2.7) does not be quadratic for \( \phi > 0 \).

4. Bayesian probability method (BP)
The Bayesian probability approach for RR is very similar to one for RD. First, we calculate the posterior distribution of \((p_1, p_2)\) and obtain the posterior distribution of \( p_1/p_2 \) by use of the variable transformation technique. Finally, we get limits of the equal tail 100(1 - \( \alpha \))% probability interval as the upper and lower 100(\( \alpha/2 \)) percentiles of the posterior distribution of \( p_1/p_2 \). In addition, these percentiles can be calculated easily using the simple Monte-Carlo method as is done for RD.

3. Examples
In this section, we view when and which type of problems can be faced in each of the methods described above through examples. Table 3.1 and Table 3.2 show the eight methods using several combinations of \( x_1, x_2, n_1, \) and \( n_2 \). Table 3.1 shows 95% limits of RD. The rows (1) and (2) represent no zero cells (NZ) with rare events, (3) to (6) depict one zero cell (OZ), and (7) and (8) are two zeros in the same row (RZ). (9) and (10) are general cases having moderate numbers. As shown in (9) and (10), if the number of events is moderate, all methods are similar although there are differences in size; the CI of the exact method are very broad while the Wilson score method and the Bayesian probability method are relatively narrow. The results are quite different when events are rare. Especially, when both events are zero, \( x_1 = 0 \) and \( x_2 = 0 \), the normal approximation method cannot calculate limits due inappropriate tethering.

Table 3.2 shows examples of RR. Rows (1) to (4) represent no zero cells (NZ) with rare events, (5) to (8) are one zero cell (OZ), and (9) and (10) are results on a general setting like in the Table 3.1. Fieller-like method seems to have a problem when events occur rarely. Most of its lower limits
interest and $\psi$. However, all Bayesian probability methods have both lower and upper limits although its point estimate is out of estimated interval limits. We discuss this more in detail in the last section.

As shown in the examples, neither RD nor RR has any problem for all methods with a moderate number of events. Only a rare event causes problems, which implies we have to choose a method with caution when handling rare events. We examine eight methods for RD and RR in the next section through Monte-Carlo simulations.

4. Simulations

We present the results of the Monte-Carlo simulation to compare the performances of the aforementioned interval estimates of RD and RR when the probability of the disease is small. For RD, we employed the study design used by Newcombe (1998b). Let $\theta = p_1 - p_2$ be a parameter of interest and $\psi = (\pi_1 + \pi_2)/2$ be a nuisance parameter. 10,240 parameter space points are chosen from sample sizes $m = 50, 60, \ldots, 200$, $n = 50, 60, \ldots, 200$. For each $(m, n)$ pair, 40 $(\psi, \theta)$ pairs are generated randomly by $\theta = \lambda[0.1 - |2\psi - 0.1|]$ and $\psi \sim U(0, 0.1)$ and $\lambda \sim U(0, 1)$ so that $0 \leq p_1 \leq 0.1$ and $0 \leq p_2 \leq 0.1$ are maintained. A total of 10,000 samples are generated in each set of the parameter $(\psi, \theta)$. For RR, we used the same design as the RD except that we generated $p_1$.

### Table 3.1. 95% confidence intervals of RD for selected contrasts

<table>
<thead>
<tr>
<th>Contrast</th>
<th>NA</th>
<th>WS</th>
<th>EX</th>
<th>BP</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1) 3/80–1/50</td>
<td>−0.0394</td>
<td>0.0744</td>
<td>−0.0709</td>
<td>0.0865</td>
</tr>
<tr>
<td>(2) 2/60–1/60</td>
<td>−0.0391</td>
<td>0.0724</td>
<td>−0.0591</td>
<td>0.0981</td>
</tr>
<tr>
<td>(3) 0/72–2/98</td>
<td>−0.0484</td>
<td>0.0075</td>
<td>−0.0713</td>
<td>0.0323</td>
</tr>
<tr>
<td>(4) 2/52–0/64</td>
<td>−0.0138</td>
<td>0.0907</td>
<td>−0.0246</td>
<td>0.1298</td>
</tr>
<tr>
<td>(5) 0/100–3/100</td>
<td>−0.0634</td>
<td>0.0034</td>
<td>−0.0845</td>
<td>0.0119</td>
</tr>
<tr>
<td>(6) 1/45–0/45</td>
<td>−0.0208</td>
<td>0.0652</td>
<td>−0.0585</td>
<td>0.1156</td>
</tr>
<tr>
<td>(7) 0/48–0/64</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>−0.0566</td>
<td>0.0741</td>
</tr>
<tr>
<td>(8) 0/75–0/75</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>−0.0487</td>
<td>0.0487</td>
</tr>
<tr>
<td>(9) 6/50–9/30</td>
<td>−0.3671</td>
<td>0.0071</td>
<td>−0.3698</td>
<td>−0.0019</td>
</tr>
<tr>
<td>(10) 54/100–20/100</td>
<td>0.2147</td>
<td>0.4652</td>
<td>0.2082</td>
<td>0.4555</td>
</tr>
</tbody>
</table>

$^f$: inappropiate tethering

### Table 3.2. 95% confidence intervals of RR for selected contrasts

<table>
<thead>
<tr>
<th>Contrast</th>
<th>NA</th>
<th>FL</th>
<th>LB</th>
<th>BP</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1) (1/10)/(2/20)</td>
<td>0.1025</td>
<td>9.7504</td>
<td>&lt; 0.0000$^f$</td>
<td>0.1694</td>
</tr>
<tr>
<td>(2) (3/80)/(1/50)</td>
<td>0.2005</td>
<td>17.5327</td>
<td>&lt; 0.0000$^f$</td>
<td>0.4728</td>
</tr>
<tr>
<td>(3) (1/20)/(1/20)</td>
<td>0.0670</td>
<td>14.9046</td>
<td>&lt; 0.0000$^f$</td>
<td>0.1603</td>
</tr>
<tr>
<td>(4) (1/200)/(2/200)</td>
<td>0.0629</td>
<td>15.8777</td>
<td>&lt; 0.0000$^f$</td>
<td>0.1590</td>
</tr>
<tr>
<td>(5) (0/72)/(2/98)</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>&lt; 0.0000$^f$</td>
<td>0.0000</td>
</tr>
<tr>
<td>(6) (0/10)/(2/15)</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>&lt; 0.0000$^f$</td>
<td>0.0000</td>
</tr>
<tr>
<td>(7) (0/100)/(3/100)</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>&lt; 0.0000$^f$</td>
<td>0.0000</td>
</tr>
<tr>
<td>(8) (0/20)/(1/20)</td>
<td>0.0000$^f$</td>
<td>0.0000$^f$</td>
<td>&lt; 0.0000$^f$</td>
<td>0.0000</td>
</tr>
<tr>
<td>(9) (6/50)/(9/30)</td>
<td>0.1580</td>
<td>1.0123</td>
<td>0.1737</td>
<td>1.1836</td>
</tr>
<tr>
<td>(10) (54/100)/(20/100)</td>
<td>1.7533</td>
<td>4.1577</td>
<td>1.8382</td>
<td>4.4832</td>
</tr>
</tbody>
</table>

$^f$: inappropriate tethering, $^\dagger$: overt overshooting, $^\ddagger$: point estimate out of limits
Table 4.1. Estimated coverage probabilities for 90%, 95%, and 99% CI of RD

<table>
<thead>
<tr>
<th>Method</th>
<th>90% coverage</th>
<th>95% coverage</th>
<th>99% coverage</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Min.</td>
<td>Mean</td>
<td>Max.</td>
</tr>
<tr>
<td>NA</td>
<td>0.1202</td>
<td>0.1204</td>
<td>0.8951</td>
</tr>
<tr>
<td>WS</td>
<td>0.8681</td>
<td>0.9395</td>
<td>0.9693</td>
</tr>
<tr>
<td>EX</td>
<td>0.2285</td>
<td>0.9755</td>
<td>0.99469</td>
</tr>
<tr>
<td>BP</td>
<td>0.8145</td>
<td>0.9169</td>
<td>0.9615</td>
</tr>
</tbody>
</table>

Table 4.2. Estimated average CI size of RD

<table>
<thead>
<tr>
<th>Method</th>
<th>90%</th>
<th>95%</th>
<th>99%</th>
</tr>
</thead>
<tbody>
<tr>
<td>NA</td>
<td>0.08773</td>
<td>0.10452</td>
<td>0.13732</td>
</tr>
<tr>
<td>WS</td>
<td>0.10045</td>
<td>0.12429</td>
<td>0.17565</td>
</tr>
<tr>
<td>EX</td>
<td>0.11093</td>
<td>0.13410</td>
<td>0.17937</td>
</tr>
<tr>
<td>BP</td>
<td>0.09724</td>
<td>0.11755</td>
<td>0.15954</td>
</tr>
</tbody>
</table>

Table 4.3. Estimated coverage probabilities for 95% CI of RD for parameter space points (number of sample points)

<table>
<thead>
<tr>
<th>Method</th>
<th>$x_1 = x_2$</th>
<th>$x_1 &gt; x_2$</th>
<th>$p_1 &lt; 0.05, p_2 &lt; 0.05$</th>
<th>$p_1 &gt; 0.05, p_2 &lt; 0.05$</th>
<th>$p_1 &gt; 0.05, p_2 &gt; 0.05$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>(640)</td>
<td>(4800)</td>
<td>(2672)</td>
<td>(4915)</td>
<td>(2653)</td>
</tr>
<tr>
<td>NA</td>
<td>0.89626</td>
<td>0.90775</td>
<td>0.78025</td>
<td>0.93135</td>
<td>0.94382</td>
</tr>
<tr>
<td>WS</td>
<td>0.97032</td>
<td>0.97171</td>
<td>0.98921</td>
<td>0.96607</td>
<td>0.95522</td>
</tr>
<tr>
<td>EX</td>
<td>0.99426</td>
<td>0.99472</td>
<td>0.99896</td>
<td>0.99429</td>
<td>0.99114</td>
</tr>
<tr>
<td>BP</td>
<td>0.96536</td>
<td>0.95973</td>
<td>0.97860</td>
<td>0.95704</td>
<td>0.95283</td>
</tr>
</tbody>
</table>

and $p_2$ from $U(0,0.1)$ and $U(0,0.1)$ respectively for simplicity.

To evaluate performances, we measure the coverage probability of interval estimates and compare with the nominal level. Coverage probabilities are compared differently depending on the observed proportions and the sample sizes.

In the Bayesian probability method, independent uniform distributions are used as the prior distributions of $p_1$ and $p_2$ to represent prior ignorance. Then, a posteriori $p_1$ and $p_2$ are independent beta distributions with parameters $(x_1 + 1, n_1 - x_1 + 1)$ and $(x_2 + 1, n_2 - x_2 + 1)$ respectively.

4.1. Risk difference

Table 4.1 displays the estimated coverage probabilities under 95%, 90%, and 99% of the nominal confidence levels. All but the normal approximation method (NA) maintain nominal levels. The mean of the coverage probabilities of the Wilson score method (WS) was similar to the Bayesian probability method (BP) but the BP has a shorter range than the WS. The NA cannot be compared with others because of the tethering problem. The BP results in the most narrow CIs, while the Exact method (EX) is most conservative. Figure 4.1 shows box plots of 95% coverage probabilities of the four methods. The horizontal line in the figure shows 95% nominal level. NA had many outliers; however, other methods resulted in short ranges. BP and WS are close to the nominal level; EX is more conservative than the others are. When we divided the results by subsets of parameters, as shown in Table 4.3, BP shows very stable coverage probabilities, however, EX and WS show higher coverage probabilities than the nominal level except when both proportions are larger than 0.05 as in the last column. In addition, NA shows lower than the nominal level except when both proportions are larger than 0.05.
Table 4.4. Estimated coverage probabilities for 95%, 90%, and 99% CI of RR

<table>
<thead>
<tr>
<th>Method</th>
<th>90% coverage</th>
<th>95% coverage</th>
<th>99% coverage</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Min.  Mean</td>
<td>Max.</td>
<td>Min.  Mean</td>
</tr>
<tr>
<td>NA</td>
<td>0.0000  0.83016 0.9388</td>
<td>0.0000  0.87153 0.9775</td>
<td>0.0086  0.89986 0.9990</td>
</tr>
<tr>
<td>FL</td>
<td>0.0000  0.69528 0.9309</td>
<td>0.0000  0.63935 0.9570</td>
<td>0.0000  0.46511 0.9860</td>
</tr>
<tr>
<td>LB</td>
<td>0.0000  0.81810 0.9184</td>
<td>0.0000  0.86080 0.9601</td>
<td>0.0000  0.89502 0.9941</td>
</tr>
<tr>
<td>BP</td>
<td>0.7342  0.90360 0.9308</td>
<td>0.8532  0.95093 0.9680</td>
<td>0.9364  0.98931 0.9949</td>
</tr>
</tbody>
</table>

4.2. Risk ratio

Table 4.4 shows the coverage probabilities for the 95%, 90%, and 99% nominal levels. Since in many cases the simulation resulted in where RR cannot be defined, we treat undefined case as zero point estimates and zero size. Normal approximation (NA), Fieller-like method (FL), and likelihood based method (LB) show zero minimum coverage because we treated and undefined case as zero and have wide ranges accordingly, whereas the Bayesian probability method (BP) is very stable throughout the range and maintains the nominal level in mean coverage. Table 4.5 shows a very large average size for the BP; however, it does not perform badly because others show a small average CI size due to tethering or overt overshooting. Figure 4.2 represents box plots for the four methods. All are skewed and have outliers shown as shaded parts in the figure. For FL, the box extends for almost the whole range and outliers are truncated by the zero value. Further, mean coverage probabilities of FL in Table 4.4 are lower than the nominal levels. In addition to the fact that limits do not exist for \( x_1 \) and/or \( x_2 = 0 \), FL appears uncommon limits when \( z_{\alpha/2} \) is large or when \( \hat{p}_2 \) is small. For rare events, BP performs well while others perform badly.
Table 4.5. Estimated average length of RR

<table>
<thead>
<tr>
<th>Method</th>
<th>90%</th>
<th>95%</th>
<th>99%</th>
</tr>
</thead>
<tbody>
<tr>
<td>NA</td>
<td>9.3393</td>
<td>12.6148</td>
<td>22.245</td>
</tr>
<tr>
<td>FL</td>
<td>31.9641</td>
<td>38.6972</td>
<td>95.166</td>
</tr>
<tr>
<td>LB</td>
<td>7.8933</td>
<td>10.1417</td>
<td>15.350</td>
</tr>
<tr>
<td>BP</td>
<td>26.5618</td>
<td>50.2463</td>
<td>227.614</td>
</tr>
</tbody>
</table>

Table 4.6. Estimated coverage probabilities for 95% CI of RR by subsets (number of sample points)

<table>
<thead>
<tr>
<th>Method</th>
<th>x₁ = x₂ (640)</th>
<th>x₁ &gt; x₂ (4800)</th>
<th>p₂ &lt; 0.05 (5120)</th>
<th>p₂ &gt; 0.05 (5120)</th>
</tr>
</thead>
<tbody>
<tr>
<td>NA</td>
<td>0.87212</td>
<td>0.84670</td>
<td>0.78272</td>
<td>0.96035</td>
</tr>
<tr>
<td>FL</td>
<td>0.63865</td>
<td>0.56388</td>
<td>0.39281</td>
<td>0.88590</td>
</tr>
<tr>
<td>LB</td>
<td>0.86086</td>
<td>0.83787</td>
<td>0.77212</td>
<td>0.94948</td>
</tr>
<tr>
<td>BP</td>
<td>0.95085</td>
<td>0.95034</td>
<td>0.94911</td>
<td>0.95276</td>
</tr>
</tbody>
</table>

Figure 4.2. Box-plots of 95% coverage probabilities for RR

Table 4.6 shows performances by subsets. We divided subset of parameters only by p₂ because the proportion of denominator is more sensitive to the results. However, regardless of subsets, the results are similar to those in Table 4.4. The results are improved when p₂ is greater than 0.05.

5. Discussion

We performed Monte Carlo simulations to evaluate various interval estimates of RD and RR when the probability of the disease to occur is small and when it is proposed for use with the Bayesian probability method. Our simulation results showed that the Wilson score method, the exact method, and the Bayesian probability method work well for RD and the normal approximation method, the likelihood based method, and the Bayesian probability method perform well for RR.
The normal approximation method of RD should be avoided when the probability of the disease to occur is small. The exact method is very conservative even when the nuisance parameter is eliminated on a restricted range. The Wilson score method performed well along with the Bayesian probability method, but it is more conservative than the Bayesian probability method. In the RR results, only Bayesian is recommended for inference of RR with rare events.

Regarding aberrations, we showed some examples of tethering and overt overshooting and examined them. The normal approximation method shows tethering for RD and Fieller-like method has many overt overshootings for RR. The Bayesian probability method for RR has an aberration resulting in some point estimates are out of estimated interval limits. The Bayesian probability method is adjusted by prior distribution. It can be used in zero event situations by adding 0.5 effect for absent cases. Four methods are compared in Table 5.1 and Table 5.2 for RR only. The tables show coverage probabilities and mean CI sizes when 0.5 is added for absent event. The results for the Bayesian probability method is the same as in the Table 4.4 and Table 4.5. The normal approximation method and the likelihood based method are improved. In contrast, the Fieller-like method does not improve by adding 0.5. The results of the likelihood based method are comparable to those of the Bayesian probability method in the coverage probabilities; however, the likelihood based method is not time-efficient because of iterative way to find limits.

The Bayesian probability method showed very good performance for both RD and RR. It does not depend on the balance of sizes between two samples and on the variety in true values of the parameter. Besides the coverage probabilities and interval size, computational simplicity is an important factor in the evaluation of interval estimates. From the computational point of view, we recommend the Bayesian probability method since the calculation of the Bayesian probability intervals only requires random number generation that can be easily done with standard software and the interval estimates of RD and RR can be constructed simultaneously using the same generated random numbers.

References


